

ON KILLING MAGNETIC CURVES IN HYPERBOLOID MODEL OF $SL(2, \mathbb{R})$ GEOMETRY

ZLATKO ERJAVEC, DAMJAN KLEMENČIĆ, AND MIHAELA LALJEK

ABSTRACT. Killing magnetic curve is a trajectory of a charged particle on a Riemannian manifold under the action of a Killing magnetic field. In this paper we study Killing magnetic curves in the Hyperboloid model of $SL(2, \mathbb{R})$ geometry.

1. INTRODUCTION

Let F be a closed 2-form on a Riemannian 3-manifold (M, g) , called the *magnetic field*. This title comes from the fact that a closed 2-form can be regarded as a generalization of a static magnetic field on 3-dim Euclidean space [15].

A curve $\gamma(t)$ on a Riemannian 3-manifold (M, g) is called a *magnetic curve* if its velocity vector field satisfies the Lorentz equation

$$\nabla_{\gamma'} \gamma' = \Phi(\gamma'), \tag{1.1} \boxed{\text{maineq}}$$

where ∇ is the Levi-Civita connection of g and Φ is $(1, 1)$ -tensor field on M , called the *Lorentz force*, related to the magnetic field F by

$$g(\Phi(X), Y) = F(X, Y), \quad \forall X, Y \in \mathfrak{X}(M). \tag{1.2} \boxed{\text{PhiF}}$$

For $\Phi = 0$, the differential equation (1.1) coincides with the geodesic equation. Hence we can say that magnetic trajectories are generalizations of geodesics.

The vector field V on M is called a *Killing vector field* if it satisfies the Killing equation

$$g(\nabla_Y V, Z) + g(\nabla_Z V, Y) = 0, \quad \forall Y, Z \in \mathfrak{X}(M). \tag{1.3} \boxed{\text{Killeq}}$$

The Killing vector field can be interpreted as an infinitesimal generator of isometry on the manifold in the sense that the flow generated by this field is a continuous isometry of the manifold.

In particular, Killing vector fields define an important class of magnetic fields called *Killing magnetic fields* and the trajectories corresponding to the Killing magnetic fields are called the *Killing magnetic curves*.

Killing magnetic curves in Euclidean 3-space \mathbb{E}^3 and Minkowski 3-spacetime \mathbb{E}_1^3 were studied by Druţă-Romaniuc and Munteanu in [5] and [4], respectively. Munteanu and Nistor considered Killing magnetic curves in $\mathbb{S}^2 \times \mathbb{R}$ space in [13], Erjavec and Inoguchi in Sol_3 space in [7] and Erjavec in Right half-space model of $SL(2, \mathbb{R})$ geometry in [7].

Key words and phrases. Magnetic curve, Killing vector field, $SL(2, \mathbb{R})$ geometry.

The goal of this paper is to study the Killing magnetic curves in the Hyperboloid model of $SL(2, \mathbb{R})$ geometry. Unique features of $SL(2, \mathbb{R})$ geometry make this task seems more complicated than in other homogeneous geometries. navesti rezultate iz RHS i ocekivanja (nismo mogli rijeiti tamo pa se nadamo da emo ovdje dobiti nove krivulje).

Let us recall that the cross product of two vector fields $X, Y \in \mathfrak{X}(M)$ on Riemannian manifold M is defined as follows

$$g(X \times Y, Z) = dv_g(X, Y, Z), \quad \forall Z \in \mathfrak{X}(M), \quad (1.4) \text{wedge}$$

where dv_g denotes a volume form on M .

It is known that in 3-dim space closed 2-form can be identified with divergence free vector fields via the Hodge operator and the volume form of the oriented manifold. If V is a Killing vector field on M , let $F_V = i_V dv_g$ be the corresponding Killing magnetic field, where i denotes the inner product on M .

Hence, the Lorentz force Φ_V corresponding to the Killing magnetic field F_V is

$$\Phi_V(X) = V \times X, \quad (1.5) \text{Phi?}$$

and then the Lorentz equation (1.1) can be written ([2]) as

$$\nabla_{\gamma'} \gamma' = V \times \gamma'. \quad (1.6) \text{main2}$$

2. $SL(2, \mathbb{R})$ GEOMETRY

Two models of $SL(2, \mathbb{R})$ geometry appear in the literature. The first one is the Right half-space model of $SL(2, \mathbb{R})$ geometry and the second one is the Hyperboloid model of $SL(2, \mathbb{R})$ geometry. Each of these two models is useful in certain contexts. These two models are isomorphic and the isomorphism between them is constructed in [6].

The Hyperboloid model is introduced in [10] and used in [3, 6, 11]. On the other side, the Right half-space model is in details explained in [14] and used in [1, 8, 9, 12]. As we mentioned, we studied Killing magnetic curves using the Right half-space model of $SL(2, \mathbb{R})$ geometry in [6].??

Briefly, we recall fundamental properties of the Hyperboloid model of $SL(2, \mathbb{R})$ geometry.

The idea is to start with the collineation group which acts on projective 3-space $\mathcal{P}^3(\mathbb{R})$ and projective sphere $\mathcal{PS}^3(\mathbb{R})$ and preserves a hyperboloid polarity, i.e. a scalar product of signature $(- - ++)$. Using the one-sheeted hyperboloid solid

$$\mathcal{H} : -x^0x^0 - x^1x^1 + x^2x^2 + x^3x^3 < 0,$$

with an appropriate choice of a subgroup of the collineation group of \mathcal{H} as an isometry group, the universal covering space $\tilde{\mathcal{H}}$ of our hyperboloid \mathcal{H} will give us the so-called hyperboloid model of $\widetilde{SL(2, \mathbb{R})}$ geometry. Details can be find in [10] and [11].

The Riemannian metric in the Hyperboloid model of $\widetilde{SL(2, \mathbb{R})}$ space is given by

$$(ds)^2 = (dr)^2 + \sinh^2 r \cosh^2 r (d\vartheta)^2 + (\sinh^2 r (d\vartheta) + (d\varphi))^2, \quad (2.1) \text{metric?}$$

where $r \in [0, \infty)$ and $\vartheta \in [-\pi, \pi)$ are polar coordinates of the intersection point of a fiber and the hyperbolic base plane and $\varphi \in (-\frac{\pi}{2}, \frac{\pi}{2})$ is a fiber coordinate with extension to \mathbb{R}

for the universal covering. One can easily see that the metric is invariant under rotations about a fiber through the origin and translations along fibers.

Therefore, the symmetric metric tensor field g is given by

$$g_{ij} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sinh^2 r \cosh 2r & \sinh^2 r \\ 0 & \sinh^2 r & 1 \end{pmatrix}. \quad (2.2) \text{ ?SLg?}$$

The Euclidean coordinates, corresponding to the hyperboloid coordinates (r, ϑ, φ) , are given by

$$\begin{aligned} x &= \tan \varphi, \\ y &= \tanh r \cdot \frac{\cos(\vartheta - \varphi)}{\cos \varphi}, \\ z &= \tanh r \cdot \frac{\sin(\vartheta - \varphi)}{\cos \varphi}, \end{aligned} \quad (2.3) \text{ ?euclideancoord}$$

. This formulas are important for later visualization of surfaces in E^3 .

The orthonormal coframe field is given by

$$\theta^1 = dr, \quad \theta^2 = \frac{1}{2} \sinh 2r \, d\vartheta, \quad \theta^3 = \sinh^2 r \, d\vartheta + d\varphi.$$

and the associated orthonormal frame field by

$$e_1 = \frac{\partial}{\partial r}, \quad e_2 = \frac{2}{\sinh 2r} \frac{\partial}{\partial \vartheta} - \tanh r \frac{\partial}{\partial \varphi}, \quad e_3 = \frac{\partial}{\partial \varphi}. \quad (2.4) \text{ [basis]}$$

Hence,

$$\partial_r = e_1, \quad \partial_{\vartheta} = \sinh r \cosh r e_2 + \sinh^2 r e_3, \quad \partial_{\varphi} = e_3. \quad (2.5) \text{ [Cbasis]}$$

In covariant derivative fashion, the Levi-Civita connection ∇ of $\text{SL}(2, \mathbb{R})$ is given by

$$\begin{aligned} \nabla_{e_1} e_1 &= 0 & \nabla_{e_1} e_2 &= -e_3 & \nabla_{e_1} e_3 &= e_2 \\ \nabla_{e_2} e_1 &= 2 \coth 2r \, e_2 + e_3 & \nabla_{e_2} e_2 &= -2 \coth 2r \, e_1 & \nabla_{e_2} e_3 &= -e_1 \\ \nabla_{e_3} e_1 &= e_2 & \nabla_{e_3} e_2 &= -e_1 & \nabla_{e_3} e_3 &= 0. \end{aligned} \quad (2.6) \text{ [covariant]}$$

Hence we have the following commutation relations of the basis

$$[e_1, e_2] = -2 \coth 2r \, e_2 - 2 \, e_3, \quad [e_1, e_3] = [e_2, e_3] = 0.$$

The non-vanishing components of Riemannian curvature tensor defined by

$$R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z,$$

up to symmetry properties, are

$$R(e_1, e_2)e_1 = 7e_2 \quad R(e_2, e_3)e_2 = -e_3 \quad R(e_1, e_3)e_1 = -e_3$$

Moreover, if we put $R_{ijkl} = -g(R_{ijk}, e_l)$, where $R_{ijk} = R(e_i, e_j)e_k$, we obtain

$$R_{1212} = -7, \quad R_{1313} = 1 \quad \text{and} \quad R_{2323} = 1.$$

3. KILLING VECTOR FIELDS IN $SL(2, \mathbb{R})$ GEOMETRY

In this section we recall basic facts on Killing vector fields and determine the Killing vector field in the Hyperboloid model of $SL(2, \mathbb{R})$ space.

Recall that the vector field V on M is a Killing vector field if it satisfies the Killing equation

$$g(\nabla_Y V, Z) + g(\nabla_Z V, Y) = 0, \quad \forall Y, Z \in \mathfrak{X}(M). \quad (3.1) \text{Killeq}$$

Let assume that the Killing vector field has a form

$$V = a(r, \vartheta, \varphi) \cdot e_1 + b(r, \vartheta, \varphi) \cdot e_2 + c(r, \vartheta, \varphi) \cdot e_3.$$

Substituting V in the relation (3.1) and taking $Y = e_i$, $Z = e_j$ for all $i, j \in \{1, 2, 3\}$, we obtain the following system of differential equations for Killing vector fields in $SL(2, \mathbb{R})$ geometry,

$$\begin{aligned} \partial_r a &= 0, & \partial_r b + \frac{2}{\sinh 2r} \partial_{\vartheta} a - \tanh r \partial_{\varphi} a - 2b \coth 2r &= 0, \\ \partial_r c + \partial_{\varphi} a - 2b &= 0, & \frac{2}{\sinh 2r} \partial_{\vartheta} b - \tanh r \partial_{\varphi} b + 2a \coth 2r &= 0, \\ \partial_{\varphi} c &= 0, & \frac{2}{\sinh 2r} \partial_{\vartheta} c - \tanh r \partial_{\varphi} c + \partial_{\varphi} b + 2a &= 0. \end{aligned} \quad (3.2) \text{Killeqsystem}$$

It is easy to check that the solutions of the (3.2) are the following vector fields

$$V_1 = e_3, \quad V_2 = \sinh 2r e_2 + \cosh 2r e_3,$$

Usually, instead in the basis of the ambient space, the Killing vector fields are given in canonical basis. Hence, using the relations (2.4) the Killing vector fields in $SL(2, \mathbb{R})$ are given by

$$\{\partial_{\varphi}, \quad 2\partial_{\vartheta} + \partial_{\varphi}\}. \quad (3.3) \text{?KillingVF?}$$

Remark 1. *Komentirati zasto samo dva, a ne 4 KVF. Since $SL(2, \mathbb{R})$ space is a line bundle over the hyperbolic plane, the vector fields V_1 , V_3 and V_4 are also Killing vector fields in hyperbolic Poincaré half-plane \mathbb{H}^2 . Vector field V_2 is a Killing vector field in the fiber direction.??? oprez: KVF su linearno nezavisni u ambijentnoj bazi, ali ne u kanonskoj.*

4. KILLING MAGNETIC CURVES IN $SL(2, \mathbb{R})$ GEOMETRY

The goal of this section is to find magnetic curves corresponding to the Killing magnetic fields in the Hyperboloid model of $SL(2, \mathbb{R})$ space.

4.1. Case A. In this subsection we consider Killing magnetic curves which correspond to the Killing vector field $V = \partial_{\varphi}$.

First task is to deduce the magnetic curve equation (1.6) for a regular curve $\gamma(t) = (r(t), \vartheta(t), \varphi(t))$ in $SL(2, \mathbb{R})$. We have

$$\gamma'(t) = r'(t) \frac{\partial}{\partial r} + \vartheta'(t) \frac{\partial}{\partial \vartheta} + \varphi'(t) \frac{\partial}{\partial \varphi},$$

and from (2.5) it follows

$$\gamma' = r'e_1 + \frac{1}{2} \sinh 2r \vartheta' e_2 + (\sinh^2 r \vartheta' + \varphi') e_3. \quad (4.1) \text{cprime}$$

Next we compute the covariant derivative $\nabla_{\gamma'} \gamma'$. Taking into account the formulas (2.6), we obtain

$$\begin{aligned} \nabla_{\gamma'} \gamma' &= \left(r'' - \frac{1}{2} \sinh 2r \vartheta' ((1 + 4 \sinh^2 r) \vartheta' + 2\varphi') \right) e_1 \\ &\quad + \left(\frac{1}{2} \sinh 2r \vartheta'' + 2(1 + 3 \sinh^2 r) r' \vartheta' + 2r' \varphi' \right) e_2 \\ &\quad + \left(\varphi'' + \sinh^2 r \vartheta'' + \sinh 2r r' \vartheta' \right) e_3. \end{aligned} \quad (4.2) \text{CD}$$

Using relation (4.1) and the formula (1.4) we have

$$V \times \gamma' = -\frac{1}{2} \sinh 2r \vartheta' e_1 + r' e_2. \quad (4.3) \text{Veks1}$$

Remark 2. *Remark The relation (4.3) we could obtain in another way. Let $dv_g = \sinh r \cosh r (dr \wedge d\vartheta \wedge d\varphi)$ be the volume element of $\text{SL}(2, \mathbb{R})$. The Killing vector field $V = \partial_\varphi$ by $F_V = i_V dv_g$, defines the magnetic field*

$$F_V(X, Y) = dv_g(X, Y, \partial_\varphi) = \frac{1}{2} \sinh 2r (dr \wedge d\vartheta)(X, Y). \quad (4.4) \text{Fphi}$$

From (1.2) and (4.4)

$$\Phi_V(\partial_r) = \frac{2}{\sinh 2r} \partial_\vartheta - \tanh r \partial_\varphi, \quad \Phi_V(\partial_\vartheta) = -\frac{1}{2} \sinh 2r \partial_r, \quad \Phi_V(\partial_\varphi) = 0.$$

Hence, from (2.5) the Lorentz force Φ_V acts on the basis vectors of $\text{SL}(2, \mathbb{R})$ as

$$\Phi_V(e_1) = e_2, \quad \Phi_V(e_2) = -e_1 \quad \Phi_V(e_3) = 0.$$

Finally we obtain the right hand side of the relation (4.3)

$$\begin{aligned} \Phi_V(\gamma') &= \Phi_V \left(r'e_1 + \frac{1}{2} \sinh 2r \vartheta' e_2 + (\sinh^2 r \vartheta' + \varphi') e_3 \right) \\ &= r'e_2 - \frac{1}{2} \sinh 2r \vartheta' e_1. \end{aligned}$$

Further, equalizing the right hand sides of the equations (4.2) and (4.3), we obtain the following system of differential equations

$$\begin{aligned} r'' - \frac{1}{2} \sinh 2r \vartheta' ((1 + 4 \sinh^2 r) \vartheta' + 2\varphi') &= -\frac{1}{2} \sinh 2r \vartheta', \\ \frac{1}{2} \sinh 2r \vartheta'' + 2(1 + 3 \sinh^2 r) r' \vartheta' + 2r' \varphi' &= r', \\ \varphi'' + \sinh^2 r \vartheta'' + \sinh 2r r' \vartheta' &= 0. \end{aligned} \quad (4.5) \text{system1}$$

Next, we solve the obtained system (4.5). By homogeneity of $SL(2, \mathbb{R})$, we can extend the solution to limit $r \rightarrow 0$, due to given assumption, as follows later on.

The third equation can be written as (total differential?)

$$\frac{d}{dt} (\varphi' + \sinh^2 r \vartheta') = 0.$$

After integrating we have

$$\varphi'(t) = C - \sinh^2 r \vartheta'(t), \quad C \in \mathbb{R}. \quad (4.6) \text{aT1}$$

Substituting (4.6) in the first equation of the system (4.5), we have

$$r'' - \frac{1}{2} \sinh 2r \vartheta' (\cosh 2r \vartheta' + (2C - 1)) = 0.$$

Hence, for $c_1 = \frac{1}{2}$ we have

$$r'' - \frac{1}{4} \sinh 4r (\vartheta')^2 = 0. \quad (4.7) \text{ar2}$$

Substituting (4.6) in the second equation of the system (4.5), we have

$$\vartheta'' + 4 \coth 2r r' \vartheta' = 0.$$

After integrating by separating of variables we obtain

$$\vartheta'(t) = \frac{k}{\sinh^2 r(t)}, \quad k \in \mathbb{R}. \quad (4.8) \text{atheta2}$$

Substituting (4.8) in the (4.7) we obtain the following differential equation

$$r'' - \frac{k \cosh 2r}{2 \sinh^3 2r} = 0. \quad (4.9) \text{ar3?}$$

Solving this equation with respect to r , we have

$$r(t) = \int_t \left(\frac{1}{2} - 2cy(\tau) + \lambda y^2(\tau) \right) d\tau. \quad (4.10) \text{aRa?}$$

In consistence with homogeneity we may consider $\lim_{t \rightarrow 0} r(t) = 0$. This implies $D = E$

At the same time we can assume $r(0) = 0; \vartheta(0) = 0; \varphi(0) = 0$, as initial conditions.

Further we consider the arc length

REFERENCES

- belk [1] M. Belkhalha, F. Dillen, J. Inoguchi: Parallel surfaces in the real special linear group $SL(2, \mathbb{R})$, *Bull. Austral. Math. Soc.* **65**, 183 (2002).
- CFG09 [2] J. L. Cabrerizo, M. Fernández, J. S. Gómez: The contact magnetic flow in 3D Sasakian manifolds, *J. Phys. A: Math. Theor.* **42**, 195201 (2009).
- erja1 [3] Z. Erjavec: On Killing magnetic curves in $\widetilde{SL(2, \mathbb{R})}$ geometry, *Math.* **14**, 413 (2009).
- DRM2 [4] S. L. Druță-Romaniuc, M. I. Munteanu: Killing magnetic curves in a Minkowski 3-space, *Nonlinear Analysis: Real World Appl.* **14**, 383 (2013).
- DRM1 [5] S. L. Druță-Romaniuc, M. I. Munteanu: Magnetic curves corresponding to Killing magnetic fields in \mathbb{E}^3 , *J. Math. Phys.* **52**, 113506 (2011).

- erja2 [6] Z. Erjavec: generalization of Cayley transformation in..., *Glasnik Mat.* **50**, 207 (2015).
- EI2 [7] Z. Erjavec, J. Inoguchi: Killing magnetic curves in Sol space, *Math. Phys. Anal. Geom.* **21**, 15 (2018).
- inog2 [8] J. Inoguchi: Invariant minimal surfaces in the real special linear group of degree 2, *Ital. J. Pure Appl. Math.* **16**, 61 (2004).
- koku [9] M. Kokubu: On minimal surfaces in the real special linear group $SL(2, \mathbb{R})$, *Tokyo J. Math.* **20**, 287 (1997).
- moln1 [10] E. Molnár: The projective interpretation of the eight 3-dimensional homogeneous geometries, *Beiträge Algebra Geom.* **38**, 261 (1997).
- moln3 [11] E. Molnár, J. Szirmai, A. Vesnin: The optimal packings by translation balls in $\widetilde{SL(2, \mathbb{R})}$, *J. of Geometry* **105**, 287 (2014).
- mont [12] S. Montaldo, I. I. Onnis, A. Passos Passamani: Helix surfaces in the special linear group, *Ann. Math. Pura Appl.* **195**, 59 (2016).
- MuNi2012 [13] M. I. Munteanu, A. I. Nistor: The classification of Killing magnetic curves in $\mathbb{S}^2 \times \mathbb{R}$, *J. Geom. Phys.* **62**, 170 (2012).
- scott [14] P. Scott: The geometries of 3-manifolds, *Bull. London Math. Soc.* **15**, 401 (1983).
- Sunada [15] T. Sunada: Magnetic flows on a Riemann surface, *Proc. KAIST Mathematics Workshop: Analysis and Geometry*, KAIST, Taejeon, Korea, 93 (1993).

(Z. E.) FACULTY OF ORGANIZATION AND INFORMATICS, UNIVERSITY OF ZAGREB, PAVLINSKA 2,
HR-42000, VARAŽDIN, CROATIA
E-mail address: zlatko.erjavec@foi.unizg.hr

(D. K.) FACULTY OF ORGANIZATION AND INFORMATICS, UNIVERSITY OF ZAGREB, PAVLINSKA 2,
HR-42000, VARAŽDIN, CROATIA
E-mail address: damjan.klemencic@foi.unizg.hr

(M. L.) FACULTY OF ORGANIZATION AND INFORMATICS, UNIVERSITY OF ZAGREB, PAVLINSKA 2,
HR-42000, VARAŽDIN, CROATIA
E-mail address: mihaela.laljek@foi.unizg.hr