

Curve acceleration in hyperboloid model of SL(2,R)

Ambient space

Coordinates in ambient space - INPUT

```
In[⊙]:= u1 := r  
        u2 :=  $\theta$   
        u3 :=  $\phi$ 
```

Metric of ambient space - INPUT

```
In[⊙]:= g[r_,  $\theta$ _,  $\phi$ _] :=  
        {{1, 0, 0}, {0, Sinh[r]2 * (Sinh[r]2 + Cosh[r]2), Sinh[r]2}, {0, Sinh[r]2, 1}}
```

```
In[⊙]:= g[u1, u2, u3] // MatrixForm // Simplify
```

Out[[⊙]]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cosh[2r] \sinh[r]^2 & \sinh[r]^2 \\ 0 & \sinh[r]^2 & 1 \end{pmatrix}$$

```
In[⊙]:= INVg := Inverse[g[u1, u2, u3]]
```

Orthonormal frame field in ambient space - INPUT

```
In[⊙]:= e1[r] := {1, 0, 0}  
        e2[r] := {0,  $\frac{1}{\cosh[r] * \sinh[r]}$ , -Tanh[r]}  
        e3[r] := {0, 0, 1}
```

Scalar product in ambient space

```
In[⊙]:= SP[v1_, v2_] := Sum[g[u1, u2, u3][[i, j]] * v1[[i]] * v2[[j]], {i, 1, 3}, {j, 1, 3}]
```

Christoffel symbols $\Gamma_{i,j}^{\{k\}} :=$

$$\frac{1}{2} \sum_{l=1}^3 (\partial_{u_i} g_{j,l} + \partial_{u_j} g_{l,i} - \partial_{u_l} g_{i,j}) h_{l,k}$$

$\text{In}[^{\circ}] := \Gamma_1[u_1, u_2, u_3] :=$

$$\text{Table}\left[\frac{1}{2} \sum_{l=1}^3 (\partial_{u_i} g[u_1, u_2, u_3][[j, l]] + \partial_{u_j} g[u_1, u_2, u_3][[l, i]] - \partial_{u_l} g[u_1, u_2, u_3][[i, j]])\right. \\ \left. \text{INVg}[[1, 1]], \{i, 1, 3\}, \{j, 1, 3\}\right] // \text{Simplify}$$

$\text{In}[^{\circ}] := \Gamma_2[u_1, u_2, u_3] :=$

$$\text{Table}\left[\frac{1}{2} \sum_{l=1}^3 (\partial_{u_i} g[u_1, u_2, u_3][[j, l]] + \partial_{u_j} g[u_1, u_2, u_3][[l, i]] - \partial_{u_l} g[u_1, u_2, u_3][[i, j]])\right. \\ \left. \text{INVg}[[1, 2]], \{i, 1, 3\}, \{j, 1, 3\}\right] // \text{Simplify}$$

$\text{In}[^{\circ}] := \Gamma_3[u_1, u_2, u_3] :=$

$$\text{Table}\left[\frac{1}{2} \sum_{l=1}^3 (\partial_{u_i} g[u_1, u_2, u_3][[j, l]] + \partial_{u_j} g[u_1, u_2, u_3][[l, i]] - \partial_{u_l} g[u_1, u_2, u_3][[i, j]])\right. \\ \left. \text{INVg}[[1, 3]], \{i, 1, 3\}, \{j, 1, 3\}\right] // \text{Simplify}$$

Basic fields

$\text{In}[^{\circ}] := w_1 := \{1, 0, 0\}$

$w_2 := \{0, 1, 0\}$

$w_3 := \{0, 0, 1\}$

Transformation matrices - canonical base $\{\partial_i\}$ vs orthonormal frame $\{e_i\}$

$$\text{In}[^{\circ}] := \text{AC} := \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\cosh[r] * \sinh[r]} & -\tanh[r] \\ 0 & 0 & 1 \end{pmatrix}$$

$\text{In}[^{\circ}] := \text{CA} = \text{Inverse}[\text{AC}]$

$\text{Out}[^{\circ}] = \{\{1, 0, 0\}, \{0, \cosh[r] \sinh[r], \sinh[r]^2\}, \{0, 0, 1\}\}$

covariant derivations of orthonormal
fields ---- $\text{CD}[i, j] = \nabla_{e_i} e_j$

$\text{In}[^{\circ}] := \text{CD}[i_, j_] :=$

$$\sum_{l=1}^3 \sum_{m=1}^3 \left(e_i[r][[l]] \left(D[e_j[r][[m]], u_l] w_m + e_j[r][[m]] \left(\sum_{n=1}^3 \Gamma_n[u_1, u_2, u_3][[l, m]] w_n \right) \right) \right)$$

Levi-Civita connection in SL(2,R) ambient space

```
In[*]:= Table[CD[i, j].CA, {i, 1, 3}, {j, 1, 3}] // MatrixForm // Simplify
```

```
Out[*]//MatrixForm=
```

$$\begin{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} & \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ \begin{pmatrix} 0 \\ \text{Coth}[r] + \text{Tanh}[r] \\ 1 \end{pmatrix} & \begin{pmatrix} -\text{Cosh}[2r] \text{Csch}[r] \text{Sech}[r] \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \\ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} & \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \end{pmatrix}$$

covariant derivation of vectors given in base of ambient space $\{e_i\}$

MAIN FORMULA

```
In[*]:= CovDer[w1_, w2_] :=
```

$$\sum_{i=1}^3 \sum_{j=1}^3 w1[[i]] * (e_i[r] [[i]] * D[w2[[j]], u_i] e_j[r].CA + w2[[j]] \times CD[i, j].CA)$$

CURVE ACCELERATION

$$\gamma(t) = r(t) e_1 + \theta(t) e_2 + \phi(t) e_3 \Rightarrow \gamma'(t) = r' e_1 + \theta' \sinh r \cosh r e_2 + (\theta' \sinh^2 r + \phi') e_3$$

$$\nabla_{\gamma'} \gamma' = ?$$

$$\text{Example11} - \nabla_{r' e_1} (r' e_1) = r'' e_1$$

```
In[*]:= CovDer[{r', 0, 0}, {r', 0, 0}] // FullSimplify
```

```
Out[*]= {0 & r', 0, 0}
```

$$\text{Example12} - \nabla_{r' e_1} (\theta' \sinh r \cosh r e_2) = -r' \theta' \sinh r \cosh r e_3 + r' \theta' \cosh 2r e_2$$

```
In[*]:= CovDer[{r', 0, 0}, {0, \theta' Sinh[r] Cosh[r], 0}] // FullSimplify
```

```
Out[*]= {0, Cosh[2r] r' \theta', -Cosh[r] Sinh[r] r' \theta'}
```

Example13 - $\nabla_{r' * e_1} (\theta' * \sinh^2 r + \phi') e_3$

```
In[*]:= CovDer[{r', 0, 0}, {0, 0, 0' (Sinh[r])^2 + 0'}] // FullSimplify
```

```
Out[*]:= {0, r' (Sinh[r]^2 0' + 0'), Sinh[2 r] r' 0'}
```

Example21 - $\nabla_{\theta' * \sinh \cosh r e_2} (r' * e_1)$

```
In[*]:= CovDer[{0, 0' Sinh[r] Cosh[r], 0}, {r', 0, 0}] // FullSimplify
```

```
Out[*]:= {0, Cosh[2 r] r' 0', Cosh[r] Sinh[r] r' 0'}
```

Example22 - $\nabla_{\theta' * \sinh \cosh r e_2} (\theta' * \sinh \cosh r e_2)$

```
In[*]:= CovDer[{0, 0' Sinh[r] Cosh[r], 0}, {0, 0' Sinh[r] Cosh[r], 0}] // FullSimplify
```

```
Out[*]:= {-1/4 Sinh[4 r] (0')^2, Cosh[r] (0 &) Sinh[r] 0', 0}
```

Example23 - $\nabla_{\theta' * \sinh \cosh r e_2} (\theta' * \sinh^2 r + \phi') e_3$ - KRIVO!

```
In[*]:= CovDer[{0, 0' Sinh[r] Cosh[r], 0}, {0, 0, 0' (Sinh[r])^2 + 0'}] // FullSimplify
```

```
Out[*]:= {-Cosh[r] Sinh[r] 0' (Sinh[r]^2 0' + 0'), 0, 0 & Sinh[r]^2 0'}
```

Example31 - $\nabla_{(\theta' * \sinh^2 r + \phi') e_3} r' * e_1$

```
In[*]:= CovDer[{0, 0, 0' (Sinh[r])^2 + 0'}, {r', 0, 0}] // FullSimplify
```

```
Out[*]:= {0, r' (Sinh[r]^2 0' + 0'), 0}
```

Example32 - $\nabla_{(\theta' * \sinh^2 r + \phi') e_3} \theta' * \sinh \cosh r e_2$

```
In[*]:= CovDer[{0, 0, 0' (Sinh[r])^2 + 0'}, {0, 0' Sinh[r] Cosh[r], 0}] // FullSimplify
```

```
Out[*]:= {-Cosh[r] Sinh[r] 0' (Sinh[r]^2 0' + 0'), 0, 0}
```

Example33 - $\nabla_{(\theta' * \sinh^2 r + \phi') e_3} (\theta' * \sinh^2 r + \phi') e_3$

```
In[*]:= CovDer[{0, 0, 0' (Sinh[r])^2 + 0'}, {0, 0, 0' (Sinh[r])^2 + 0'}] // FullSimplify
```

```
Out[*]:= {0, 0, 0 & (Sinh[r]^2 0' + 0')}
```

generally ---KRIVO!

$\nabla_{\gamma'} \gamma'$

```
In[e]:= CovDer[{r',  $\theta'$  Sinh[r] Cosh[r],  $\theta'$  (Sinh[r])2 +  $\phi'$ },
               {r',  $\theta'$  Sinh[r] Cosh[r],  $\theta'$  (Sinh[r])2 +  $\phi'$ }] // FullSimplify
Out[e]= { $\theta' r' + \frac{1}{2} \sinh[2r] \theta' ((1 - 2 \cosh[2r]) \theta' - 2 \phi')$ ,
           $\frac{1}{2} (\theta' \sinh[2r] + (-2 + 6 \cosh[2r]) r') \theta' + 2 r' \phi'$ ,
           $2 \sinh[r] (\theta' \sinh[r] + \cosh[r] r') \theta' + \theta' \phi'$ }
```

Provjera identiteta

```
In[e]:= (1 - 2 Cosh[2 r]) - (-1 - 4 (Sinh[r])2) // FullSimplify
Out[e]= 0

In[e]:= (-1 + 3 Cosh[2 r]) - 2 (1 + 3 (Sinh[r])2) // FullSimplify
Out[e]= 0
```

Usporedba članova akceleracije uz e1

```
In[e]:= DM1 := r'' - ( $\theta'$ )2 Sinh[r] Cosh[r] Cosh[2 r] -
           2 ( $\theta'$ )2 (Sinh[r])3 Cosh[r] - 2  $\theta' \phi'$  Sinh[r] Cosh[r]
          EZ1 := r'' - Sinh[r] Cosh[r]  $\theta'$  ((1 + 4 (Sinh[r])2)  $\theta'$  + 2  $\phi'$ )
In[e]:= DM1 - EZ1 // FullSimplify
Out[e]= 0
```

Usporedba članova akceleracije uz e2

```
In[e]:= DM2 := 2 r'  $\theta'$  Cosh[2 r] + 2 r'  $\theta'$  (Sinh[r])2 + 2 r'  $\phi'$  +  $\theta''$  Sinh[r] Cosh[r]
          EZ2 := Sinh[r] Cosh[r]  $\theta''$  + 2 (1 + 3 (Sinh[r])2) r'  $\theta'$  + 2 r'  $\phi'$ 
In[e]:= DM2 - EZ2 // FullSimplify
Out[e]= 0
```

Usporedba članova akceleracije uz e3

```
In[e]:= DM3 :=  $\phi''$  + r'  $\theta'$  Sinh[2 r] +  $\theta''$  (Sinh[r])2
          EZ3 :=  $\phi''$  + (Sinh[r])2  $\theta''$  + Sinh[2 r] r'  $\theta'$ 
In[e]:= DM3 - EZ3 // FullSimplify
Out[e]= 0
```