

Inference

Overview

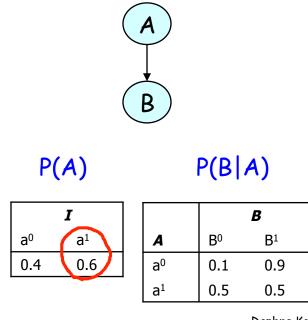
MAP Inference

Maximum a Posteriori (MAP)

- Evidence: E=eQuery: all other variables $Y(Y=\{X_1,...,X_n\}-E)$ the • Evidence: E=e
- Task: compute MAP(Y|E=e) = argmax, P(Y=y | E=e) - Note: there may be more than one possible solution
- Applications
 - Message decoding: most likely transmitted message
 - Image segmentation: most likely segmentation

MAP ≠ Max over Marginals

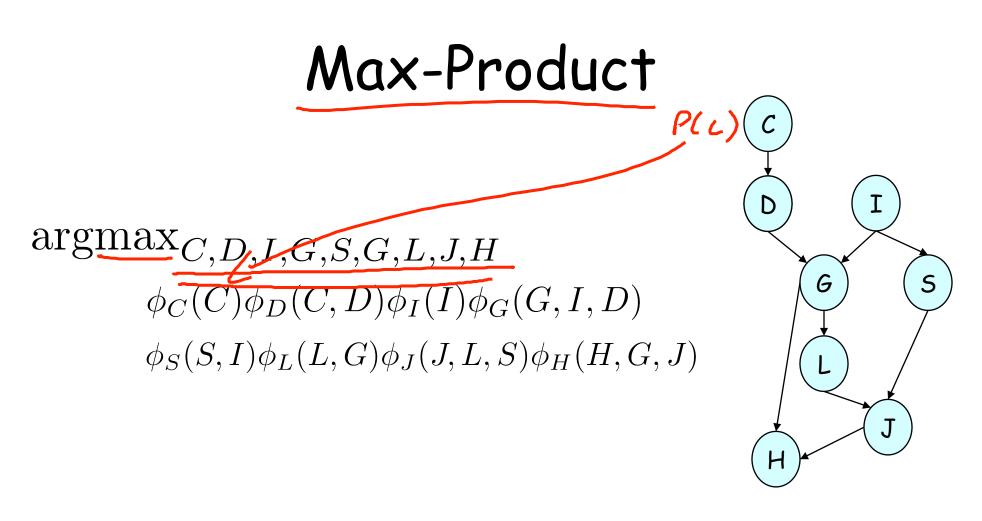
• Joint distribution $-P(a^{0}, b^{0}) = 0.04$ $-P(a^{0}, b^{1}) = 0.36$ $-P(a^{1}, b^{0}) = 0.3$ $-P(a^{1}, b^{1}) = 0.3$

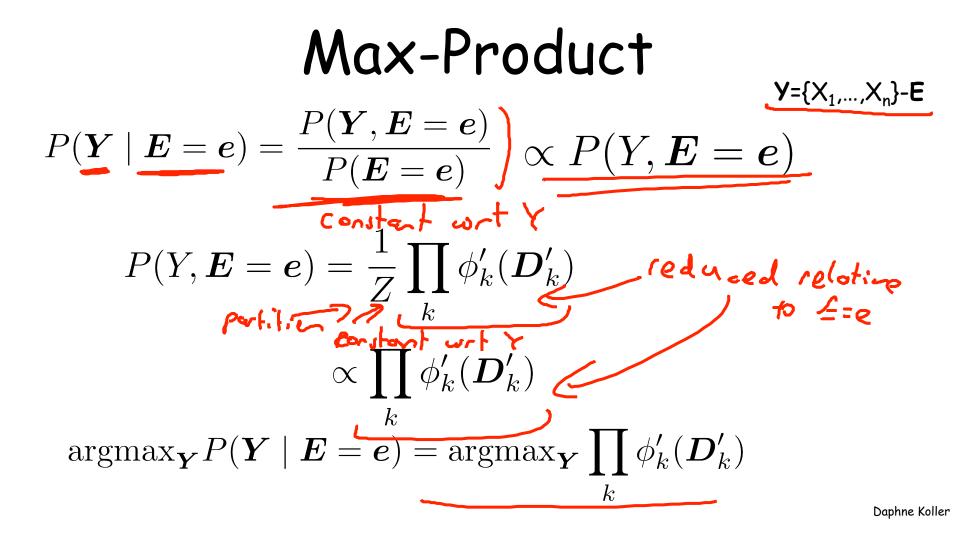


NP-Hardness

The following are NP-hard

- Given a PGM P_{Φ} , find a joint assignment x with highest probability $P_{\Phi}(x)$
- Given a PGM P_{Φ} and a probability p, decide if there is an assignment x such that $P_{\Phi}(x) > p$





Algorithms: MAP

- Push <u>maximization</u> into <u>factor product</u>
 Variable elimination <u>Max</u> <u>max</u>
- Message passing over a graph

 Max-product belief propagation
- Using methods for integer programming
- For some networks: graph-cut methods
- Combinatorial search

Summary

- MAP: <u>single coherent assignment</u> of highest probability
 - Not the same as maximizing individual marginal probabilities
- Maxing over factor product
- Combinatorial optimization problem
- Many exact and approximate algorithms